

Air Virtual At Sea (VAST) Platform Stimulation Analysis

Final Report Concept for Support of ONR/JFCOM

Contract N00014-04-M-0074 CLIN 0001AC

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Outline

- VAST / LVC Integration Concept
- VAST / LVC Integration Architecture
 - Notional
 - Component
- Demonstration Concept
 - Phase 1
 - Phase 2
 - Phase 3 ('06 opportunity)
- Schedule and Cost
- Engineering Management Topics





VAST / LVC Integration Concept

- Goal: Concept exploration of bi-directional stimulation of live, airborne platforms and a synthetic battlespace environment.
- Objective: Enhance LVC infrastructure in the Hawaiian Islands
 - Maui High Performance Computing Center (MHPCC)
 - Kauai Pacific Missile Range Facility (PMRF)
- Extend MSR infrastructure to include stimulation of a generic live node sensor system with virtual and constructive state information
- Integrate newly developed MSR infrastructure into the JTEN





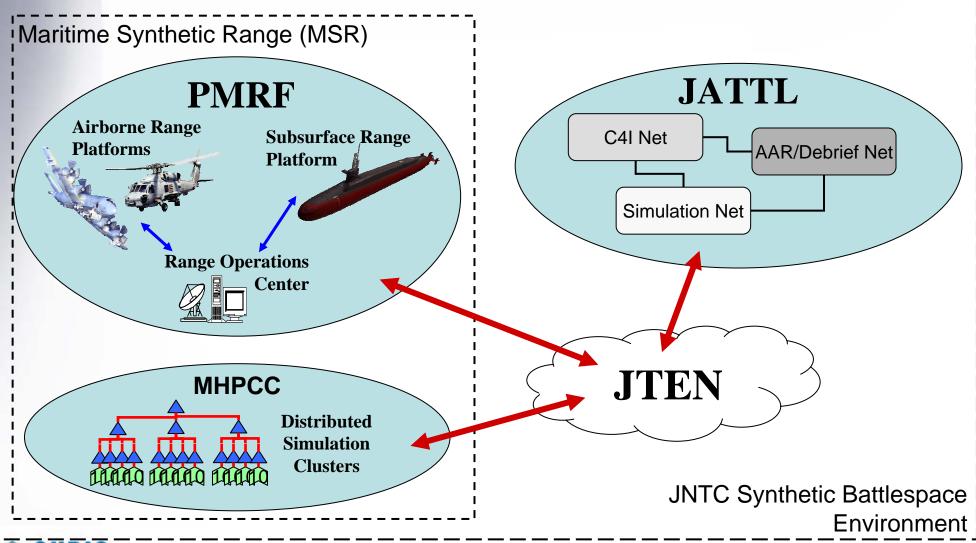
VAST / LVC Integration Approach

- Develop a demonstration concept based on leveraging emergent technologies and existing core LVC technologies.
- Leverage P5CTS development to support platform integration; Use of P5CTS will complement the P5CTS program goals on a non-interference basis
 - Performs early risk reduction for P5CTS in the simulation/stimulation area
 - Uses contractor assets as P5 surrogate hardware for demos
 - Takes advantage of Cubic advanced systems engineering group domain knowledge in TACTS/ACMI especially P5
- As required, reuse/leverage surrogate platform integration technologies (e.g., ASW VAST MRT3, ONR LCASS)
- Leverage standardized JNTC / NCTE simulation/stimulation technologies (to include network infrastructure).



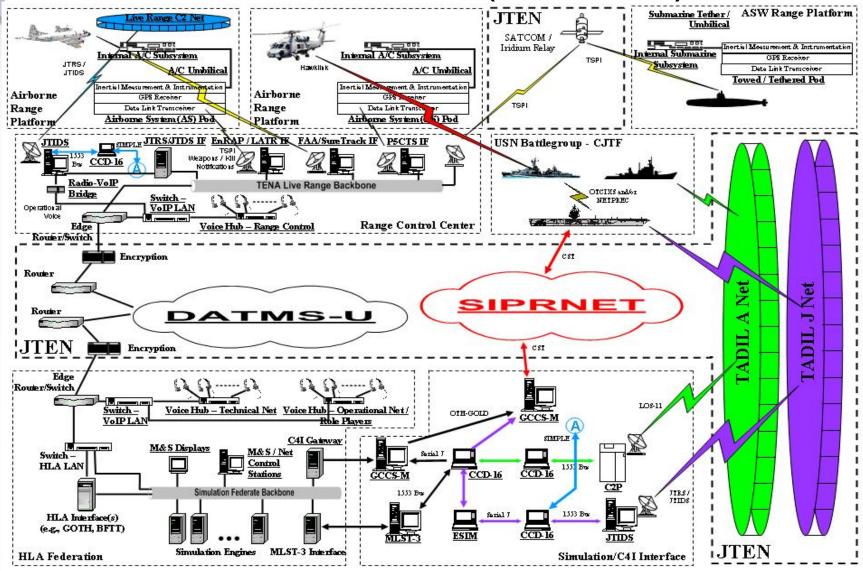
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VAST/LVC Integration Conceptual Architecture





VAST/LVC Component Architecture (Notional)





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Component Technologies

- ASW Platforms SH-60B ('05), P-3C ('06), SSN ('06)
- Platform Stimulation P5CTS, LCASS (like technologies),
 TATS, range voice communications and circuits
- Platform Interface P5CTS, LCASS, Towed Array Antenna,
 Organic sensors and transceivers, P5CTS TENA interface
- Networking JTEN, SDREN/DREN, TENA⇔HLA interfaces, LVC Bridge
- Simulation JNTC Toolkit (e.g., JSAF, FAARS, MARCI)
- C4I Alternative C4I GW, GCCS, TADIL (MLST3)





Demonstration Concept

- ASW mission
 - Technology demonstration
 - ASW training in context of Joint Operations
- Incremental capabilities; spiraling integration
 - Range Integration
 - Airborne platforms
 - Subsurface
 - JATTL/MHPCC Integration
- On- and Off-platform stimulation using distributed computing technologies
- Two Phase Demonstration Approach





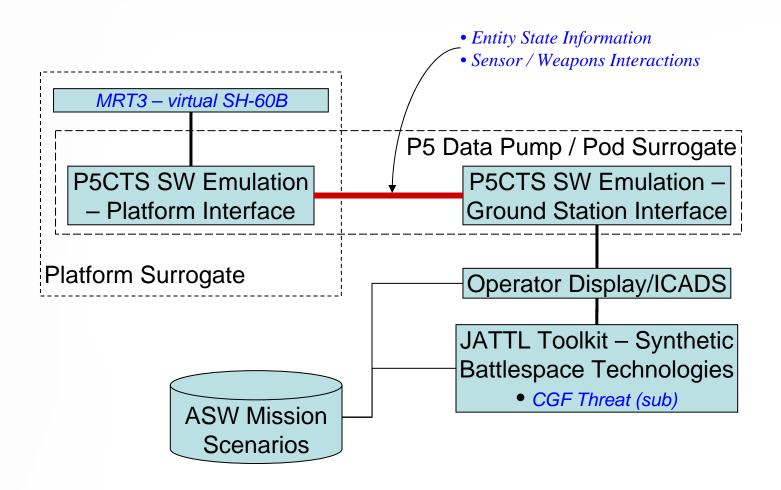
Phase 1 Demo Concept

- Evolve and develop Use Cases/Scenarios
- Develop Demo System Architecture/SRD
- Develop ASW constructive simulation/stimulation models for SH-60/P-3C and submarine target
- Develop / enhance operator displays to include RWR and ASW views
- Create P5 data pump and integrate with constructive simulator
- Perform Lab Demo of ASW training concept using constructive simulator/stimulator and P5 data pump



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Phase 1 Demo Architecture







Phase 1 Demo Technical Approach

- Reuse of ASW VAST / MRT3 (SH-60B)
- Design reusable data model for platform stimulation
- Develop prototype P5CTS SW components required for demonstration of concept
- Modify operator displays and constructive simulation components to manage data flow and component interfaces
- Restrict effort and development activities to SW components and component interfaces





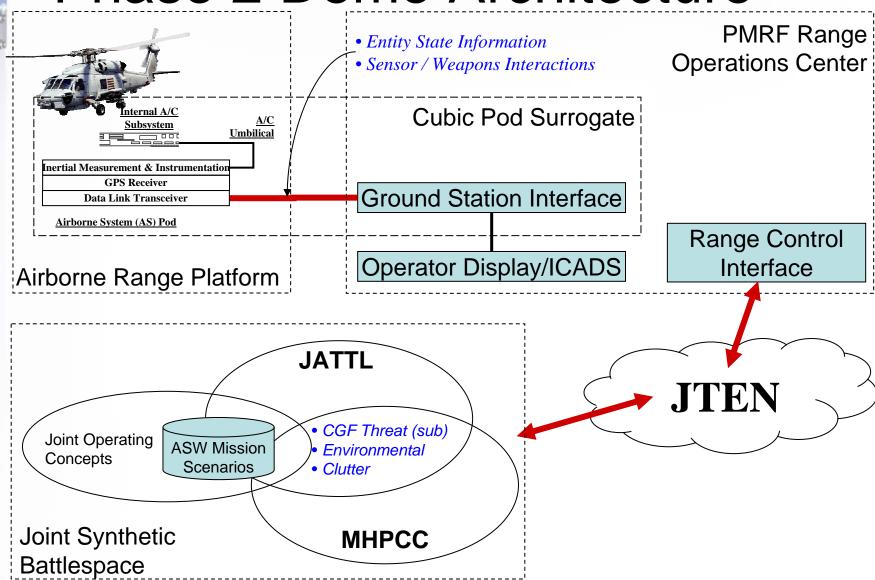
Phase 2 Demo Concept

- Replace ASW VAST MRT3 (virtual simulator) w/ instrumented SH-60/P3C for ASW platform
 - Uses existing Cubic pod inventory
 - Enhance Cubic pods to perform as P5 surrogate
- Integrate PMRF into larger Joint synthetic battlespace using JTEN
 - Develop PMRF⇔TENA⇔HLA Interface
 - Stimulate PMRF airborne platform environment using JATTL Toolkit
 - Utilize MHPCC for large-scale, high-density battlespace; environmental/clutter modeling
- Retain constructive (CGF) threat environment (i.e., submarine target)



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Phase 2 Demo Architecture







Demo Phase 2 Technical Approach

- Utilize Cubic Pod surrogate technologies to integrate PMRF airborne range platform
- Demonstrate stimulation of aircraft subsystems
- Integrate platform stimulation at Mayport NS, NAS Jax, or NAS North Island
- Develop key PMRF network/data interfaces based on JATTL interoperability requirements
- Demonstration scenario to incorporate JNTC-based
 Joint Operating Concepts that include ASW operations





Demo Phase 2 Risks

- Risk: Availability of airborne platforms
 - Mitigation: Use of virtual surrogates; modify end-toend architecture to include reusable components
- Risk: Availability of P5 hardware
 - Mitigation: Use of LCASS technologies as HW surrogate
- Risk: Aggressive development schedule
 - Mitigation: Technology leveraging/reuse
 - restrict system capabilities to only show simple dataflow





Demo Phase 3 Concept

- Phase 3 Evolutionary Step ('06 opportunity)
 - Replaces constructive simulated submarine target with live submarine target; integrated in-range and open ocean communications (i.e., acoustic modem and tow array antenna technologies)
 - Field updated system at PMRF and JATTL facilities
 - Adds a AF asset such as E3
 - Generate report on lessons learned and risk mitigation
 recommendations for sustaining Joint / ASW mission training capabilities
- Phase 3 Baseline
 - Retains instrumented SH-60 or P3C for ASW platform with surrogate P5 hardware
 - Uses TENA and JTEN for link between JATTL and PMRF





POA&M

Plan of Action and Milestones

+ 45 Days

Outlines major MSR/JTEN engineering milestones

Systems Requirements Document (SRD)

+ 60 Days

Architecture (DODAF Views)

+ 9 Months

System Integration and Test Plan

+ 10 Months

Demonstration

+ 12 Months





ROM Cost

- Labor \$400,000
- Travel \$ 20,000
- ODC -\$ 5,000
- Hardware \$ 60,000
- Contract Service \$ 15,000
- Total \$500,000



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Critical Engineering Management Activities

- Project Management Planning
 - Schedule management
 - Recurring technical risk assessment and mitigation
- Requirements analysis / Architecture development
 - Focus on functional vs. non-functional requirements
 - Emphasis on technical requirements for key interface components
 - Identify high-value (meaningful and useful) data exchanges to effectively demonstrate stimulation of platform subsystems.
- Incremental integration and test processes
 - Required to effectively manage complex scope of component interfaces
 - Tight feedback loop with management planning (i.e., risk management)
- Control of HW/SW releases and system documentation (CM)
 - Coordination with other programs developing dependent technologies
 - To provide sustainment of demonstration capabilities and support transition/evolution of integrated VAST and LVC technologies





Sustaining Infrastructure

- Architecture and concept
 - Develop conformant w/JNTC std. (DoDAF)
 - Develop CONOPS for service specific mission training w/JTT
- Pod interfaces
 - Establish technical migration path to utilization of P5CTS technologies
 - Develop prototype operational configuration and control components
- JATTL interfaces
 - Develop baseline networking / data translation technologies
 - Maintain within the existing JATTL CM framework / infrastructure
- Integration methodology
 - Documented procedures and technical integration plans
 - Appropriate methodology to manage classified and secure integration w/JATTL





Summary

- A feasible approach exists to integrate operations of PMRF range platforms with JATTL to support Joint training
- Engineering solution relies on the reuse and leveraging of existing/emergent technologies
- An achievable plan exists to demonstrate the concept of VAST / LVC Integration
- The proposed VAST / LVC Integration can be achieved
 - Low-to-moderate technical risks
 - Moderate-to-high schedule risks
 - Low-to-moderate risk within proposed funding

